# **BC-30 ROB/AIBO (Robotic)**

### **Substation UV+IR+VIS Inspection Automation**

BC-30 ROB & BC-30 AlBO is an intelligent robotic corona detecting tool with UV, IR and VIS multiple spectrum imaging systems integrated with robot (ROB) and robot dog (AlBO). It can simultaneously detect the invisible corona of the human eye or the faint UV rays radiated by the partial discharge of the surface. The IR rays emitted by the current heating and the high-definition VIS 24 hours a day perform real-time positioning observation and quantitative indication through the image. The intelligent inspection management platform includes a smart robot body, robot self-management system, inspection management system, and remote centralized control management system. Personnel deployment, reliability of results, fault handling, information exchange, operation and maintenance efficiency make all power defects nowhere to hide.

We can load our UV Camera set on the robot wheel (30-ROB) and robot dog (30-ROB-AIBO). The bundle package will give a hassle-free turnkey solution for your robotic project. You may also recruit your choice of robots to match our camera system as a custom option.





BC-30 AIBO (Robot Dog)

Real-time photon counting of corona for quantitative analysis

Out-of-band rejection filter technology, not affected by sunlight

IP 55 protection, high sensitivity dynamic obstacle avoidance ability

IR temperature measurement with high precision and a wide range

One-stop intelligent inspection management platform

Multi-spectral image auto-focusing and taking photos to facilitate real-time observation

Powerful 8- drive chassis facilitates multi-directional driving

Using a 2.4GHZ high-frequency radio communication range

Multi-spectral synchronization, no delay and tailing, accurate positioning corona

Endurance time is more than eight hours, meeting the demand of daytime operation

PC, remote control, manual and automatic integrated control, humanized design

Stable working temperature from -20  $^{\circ}$ C  $^{\sim}$  +60  $^{\circ}$ C

High-precision LIDAR navigation to accurately locate the driving route

Customized to specific applications

### 1. FEATURES

#### **Super Protection Ability for harsh environment**

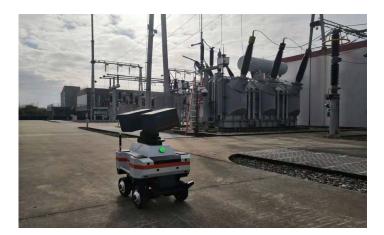
Designed for substation working environment, with superior protection ability, equipped with obstacle avoidance system, extreme anti- collision protection system and anti-drop system No fear of harsh environment, super anti-plateau wind and sand, anti-electromagnetic interference, antihigh noise capabilities, waterproof and wading capabilities.

#### Multi-sensor, Multi-spectrum, Integrated Intelligent Technology

Advanced audio and video recognition technology, capture abnormalities, accurately and efficiently Using high resolution IR imaging system with a temp range of -20 to 650°C, accurate IR image temperature measurement and analysis ability. Smart camera with 30 times optical zoom, 1080P high resolution. Use high sensitivity UV detection sensor.

#### Autonomous Intelligent Inspection without Manual Intervention

Fully automatic round-the-clock inspection, intelligent navigation, route planning, independent charging, without conventional human intervention.



#### **Intelligent Inspection Management Platform**

Intelligent inspection robot self-management system, smart inspection management system, inspection remote centralized control management system and other systems integrated to solve the problem of personnel deployment, result reliability, fault handling, information delay, operation and maintenance in the traditional inspection efficiency etc.

#### Real-time report, Intelligent prediction based on bid data

The self-developed advanced data model generates visual data analysis reports in real time. Combining previous data, environmental data and other sensors of the entire network, etc. Multi-dimensional Integrated calculations to realize intelligent trend prediction and real-time abnormal warning

# Network-wide Linkage for all Substation Information, Intelligent Diagnosis

Real-time linkage of all the information of entire network, fully supporting compatible sharing of information with different suppliers and manufacturers, uninterrupted communication, overview of the whole, and intelligent decision- making.





## 2. TECHNICAL SPECIFICATIONS

Field Of Vision (W x S)	CHARACTERISTICS OF UV CHANNEL		
Minimum Discharge Sensitivity	Field Of Vision (W x S)	12.6° x 7.2° & 5.0° x 3.75°	
Minimum UV Sensitivity  Pixel  1280 x 720  CHARACTERISTICS OF IR CHANNEL  Image Resolution  640 x 480  Focusing Method  Focusing Method  Fold of Vision (W x S)  Range & Accuracy of Temperature Measurement  -20°C ~ 650°C, ±2°C/2%  CHARACTERISTICS OF VIS CHANNEL  Image Resolution  1920 x 1080  Focusing Method & Zoom  Auto / Manual Focus, Optical; x 30, Digital x 20  PARAMETER OF PAN-TILT  Horizontal & Vortical Scanning Range  780°, -10° ~ 90°  Preset Points  CONTROL MODE  Control Mode  Auto / Manual Control  Control Terminal  PC, Remote Control  NAVIGATION SYSTEM  Navigation Method / Accuracy  COMMUNICATION CAPABILITIES (CUSTOMIZABLE)  Wireless Communication  Maximum Communication Bandwidth & Distance  MOVEMENT & WADE BARRIER ABILITY  Vehicle Speed  Parking Positioning Accuracy  Cradeability  Obstacle Crossing Ability  Wading Ability  Ground Ponding<100mm	Range of Wavelength	240nm ~ 280nm	
Pixel 1280 x 720  CHARACTERISTICS OF IR CHANNEL  Image Resolution 640 x 480  Focusing Method Auto / Manual Focus  Field Of Vision (W x S) 25° x 19°  Range & Accuracy of Temperature Measurement -20° C ~ 650° C, ±2° C/2%  CHARACTERISTICS OF VIS CHANNEL  Image Resolution 1920 x 1080  Focusing Method & Zoom Auto / Manual Focus, Optical; x 30, Digital x 20  PARAMETER OF PAN-TILT  Horizontal & Vertical Scanning Range 360°, -10° ~ 90°  Preset Points >8000 (Customizable)  CONTROL MODE  Control Mode Auto / Manual Control  Control Terminal PC, Remote Control  NAVIGATION SYSTEM  Navigation Method / Accuracy  COMMUNICATION CAPABILITIES (CUSTOMIZABLE)  Wireless Communication  Maximum Communication Bandwidth & Distance 20Mbps, 1000m  MOVEMENT & WADE BARRIER ABILITY  Vehicle Speed 1m/s°  Parking Positioning Accuracy ±10mm  Cordadability >15°  Conding Ability Ground Ponding<100mm	Minimum Discharge Sensitivity	1Pc/10m	
CHARACTERISTICS OF IR CHANNEL  Image Resolution 640 x 480  Focusing Method Auto / Manual Focus  Field Of Vision (W x S) 25" x 19"  Range & Accuracy of Temperature Measurement -20"C ~ 650"C, ±2"C/2%  CHARACTERISTICS OF VIS CHANNEL  Image Resolution 1920 x 1080  Focusing Method & Zoom Auto / Manual Focus, Optical; x 30, Digital x 20  PARAMETER OF PAN-TILT  Horizontal & Vertical Scanning Range 360", -10" ~ 90"  Preset Points >8000 (Customizable)  CONTROL MODE  Control Mode Auto / Manual Control  Control Terminal PC, Remote Control  NAVIGATION SYSTEM  Navigation Method / Accuracy Lidar, ±10mm  COMMUNICATION CAPABILITIES (CUSTOMIZABLE)  Wireless Communication 2.4GHz High-Frequency Radio Station  Maximum Communication Bandwidth & Distance 20Mbps, 1000m  MOVEMENT & WADE BARRIER ABILITY  Vehicle Speed 1m/s"  Parking Positioning Accuracy ±10mm  Gradeability >15"  Obstacle Crossing Ability Ground Ponding<100mm	Minimum UV Sensitivity	2 x 10 <sup>-18</sup> watt/cm <sup>2</sup>	
Image Resolution 640 x 480  Focusing Method Auto / Manual Focus  Field Of Vision (W x S) 25" x 19"  Range & Accuracy of Temperature Measurement -20"C ~ 650"C, ±2"C/2%  CHARACTERISTICS OF VIS CHANNEL  Image Resolution 1920 x 1080  Focusing Method & Zoom Auto / Manual Focus, Optical; x 30, Digital x 20  PARAMETER OF PAN-TILT  Horizontal & Vertical Scanning Range 360", -10" ~ 90"  Preset Points >8000 (Customizable)  CONTROL MODE  Control Mode Auto / Manual Control  Control Terminal PC, Remote Control  NAVIGATION SYSTEM  Navigation Method / Accuracy Lidar, ±10mm  COMMUNICATION CAPABILITIES (CUSTOMIZABLE)  Wireless Communication 2.4GHz High-Frequency Radio Station  Maximum Communication Bandwidth & Distance 20Mbps, 1000m  MOVEMENT & WADE BARRIER ABILITY  Vehicle Speed 1m/s*  Parking Positioning Accuracy ±10mm  Gradeability >15"  Obstacle Crossing Ability Ground Ponding<100mm	Pixel	1280 x 720	
Focusing Method  Field Of Vision (W x S)  Range & Accuracy of Temperature Measurement  -20°C ~ 650°C, ±2°C/2%  CHARACTERISTICS OF VIS CHANNEL  Image Resolution  Focusing Method & Zoom  PARAMETER OF PAN-TILT  Horizontal & Vertical Scanning Range  Preset Points  CONTROL MODE  Control Mode  Control Terminal  NAVIGATION SYSTEM  Navigation Method / Accuracy  COMMUNICATION CAPABILITIES (CUSTOMIZABLE)  Wireless Communication  Maximum Communication Bandwidth & Distance  MOVEMENT & WADE BARRIER ABILITY  Vehicle Speed  Parking Positioning Accuracy  Gradeability  Wading Ability  Ground Ponding<1000  Lidar, ±10mm  Communication  1m/s°  2num Ponding<100mm  Wading Ability  Ground Ponding<100mm	CHARACTERISTICS OF IR CHANNEL		
Field Of Vision (W x S)  Range & Accuracy of Temperature Measurement  -20°C ~ 650°C, ±2°C/2%  CHARACTERISTICS OF VIS CHANNEL  Image Resolution  1920 x 1080  Focusing Method & Zoom  Auto / Manual Focus, Optical; x 30, Digital x 20  PARAMETER OF PAN-TILT  Horizontal & Vertical Scanning Range  78000 (Customizable)  CONTROL MODE  Control Mode  Control Mode  Auto / Manual Control  Control Terminal  NAVIGATION SYSTEM  Navigation Method / Accuracy  COMMUNICATION CAPABILITIES (CUSTOMIZABLE)  Wireless Communication  Maximum Communication Bandwidth & Distance  Movement & Wade Barrier Ability  Vehicle Speed  1m/s°  Parking Positioning Accuracy  (Gradeability  Obstacle Crossing Ability  Figure 1.20°C ~ 650°C, ±2°C/2%  4000	Image Resolution	640 x 480	
Range & Accuracy of Temperature Measurement  CHARACTERISTICS OF VIS CHANNEL  Image Resolution  Focusing Method & Zoom  Auto / Manual Focus, Optical; x 30, Digital x 20  PARAMETER OF PAN-TILT  Horizontal & Vertical Scanning Range  Preset Points  CONTROL MODE  Control Mode  Control Terminal  NAVIGATION SYSTEM  Navigation Method / Accuracy  Wireless Communication  Maximum Communication Bandwidth & Distance  MOVEMENT & WADE BARRIER ABILITY  Vehicle Speed  Parking Positioning Accuracy  Gradeability  Obstacle Crossing Ability  Wading Ability  Focusing Method & Control Terminal  - 2.0°C ~ 650°C, ±2°C/2%  1920°C ~ 650°C, ±2°C/2%  4uto / Manual Focus, Optical; x 30, Digital x 20  Auto / Manual Focus, Optical; x 30, Digital x 20  Auto / Manual Focus, Optical; x 30, Digital x 20  Auto / Manual Control  Auto / Manual Control  PC, Remote Control  Lidar, ±10mm  2.4GHz High-Frequency Radio Station  2.4GHz High-Frequency Radio Station  1m/s°  Parking Positioning Accuracy  ±10mm  Gradeability  Obstacle Crossing Ability  Ground Ponding<100mm	Focusing Method	Auto / Manual Focus	
CHARACTERISTICS OF VIS CHANNEL  Image Resolution 1920 x 1080  Focusing Method & Zoom Auto / Manual Focus, Optical; x 30, Digital x 20  PARAMETER OF PAN-TILT  Horizontal & Vertical Scanning Range 360°, -10° ~ 90°  Preset Points >8000 (Customizable)  CONTROL MODE  Control Mode Auto / Manual Control  Control Terminal PC, Remote Control  NAVIGATION SYSTEM  Navigation Method / Accuracy Lidar, ±10mm  COMMUNICATION CAPABILITIES (CUSTOMIZABLE)  Wireless Communication 2.4GHz High-Frequency Radio Station  Maximum Communication Bandwidth & Distance 20Mbps, 1000m  MOVEMENT & WADE BARRIER ABILITY  Vehicle Speed 1m/s°  Parking Positioning Accuracy ±10mm  Gradeability >15°  Obstacle Crossing Ability Ground Ponding<100mm	Field Of Vision (W x S)	25° x 19°	
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Focusing Method & Zoom  Auto / Manual Focus, Optical; x 30, Digital x 20  PARAMETER OF PAN-TILT  Horizontal & Vertical Scanning Range  Preset Points  CONTROL MODE  Control Mode  Control Terminal  NaVIGATION SYSTEM  Navigation Method / Accuracy  COMMUNICATION CAPABILITIES (CUSTOMIZABLE)  Wireless Communication  Maximum Communication Bandwidth & Distance  MOVEMENT & WADE BARRIER ABILITY  Vehicle Speed  Parking Positioning Accuracy  £10mm  1m/s°  Parking Positioning Accuracy  £10mm  Gradeability  Obstacle Crossing Ability  Ground Ponding<100mm	CHARACTERISTICS OF VIS CHANNEL		
PARAMETER OF PAN-TILT  Horizontal & Vertical Scanning Range Preset Points  CONTROL MODE  Control Mode Control Terminal NAVIGATION SYSTEM Navigation Method / Accuracy COMMUNICATION CAPABILITIES (CUSTOMIZABLE)  Wireless Communication Maximum Communication Bandwidth & Distance MOVEMENT & WADE BARRIER ABILITY  Vehicle Speed Parking Positioning Accuracy Gradeability Obstacle Crossing Ability  Wading Ability  360°, -10° ~ 90° A60°, -	Image Resolution	1920 x 1080	
Horizontal & Vertical Scanning Range Preset Points  CONTROL MODE  Control Mode Auto / Manual Control  Control Terminal PC, Remote Control  NAVIGATION SYSTEM Navigation Method / Accuracy Lidar, ±10mm  COMMUNICATION CAPABILITIES (CUSTOMIZABLE)  Wireless Communication Maximum Communication Bandwidth & Distance MOVEMENT & WADE BARRIER ABILITY  Vehicle Speed 1m/s°  Parking Positioning Accuracy £10mm  Maximum Communication Formunication F	Focusing Method & Zoom	Auto / Manual Focus, Optical; x 30, Digital x 20	
Preset Points >8000 (Customizable)  CONTROL MODE  Control Mode Auto / Manual Control  Control Terminal PC, Remote Control  NAVIGATION SYSTEM  Navigation Method / Accuracy Lidar, ±10mm  COMMUNICATION CAPABILITIES (CUSTOMIZABLE)  Wireless Communication 2.4GHz High-Frequency Radio Station  Maximum Communication Bandwidth & Distance 20Mbps, 1000m  MOVEMENT & WADE BARRIER ABILITY  Vehicle Speed 1m/s°  Parking Positioning Accuracy ±10mm  Gradeability >15°  Obstacle Crossing Ability 50mm  Wading Ability Ground Ponding<100mm	PARAMETER OF PAN-TILT		
CONTROL MODE  Control Mode  Auto / Manual Control  Control Terminal  NAVIGATION SYSTEM  Navigation Method / Accuracy  Lidar, ±10mm  COMMUNICATION CAPABILITIES (CUSTOMIZABLE)  Wireless Communication  Maximum Communication Bandwidth & Distance  MOVEMENT & WADE BARRIER ABILITY  Vehicle Speed  Parking Positioning Accuracy  E10mm  Gradeability  Obstacle Crossing Ability  Ground Ponding<100mm	Horizontal & Vertical Scanning Range	360°, -10° ~ 90°	
Control Mode Auto / Manual Control  Control Terminal PC, Remote Control  NAVIGATION SYSTEM  Navigation Method / Accuracy Lidar, ±10mm  COMMUNICATION CAPABILITIES (CUSTOMIZABLE)  Wireless Communication 2.4GHz High-Frequency Radio Station  Maximum Communication Bandwidth & Distance 20Mbps, 1000m  MOVEMENT & WADE BARRIER ABILITY  Vehicle Speed 1m/s°  Parking Positioning Accuracy ±10mm  Gradeability >15°  Obstacle Crossing Ability 50mm  Wading Ability Ground Ponding<100mm	Preset Points	>8000 (Customizable)	
Control Terminal PC, Remote Control  NAVIGATION SYSTEM  Navigation Method / Accuracy Lidar, ±10mm  COMMUNICATION CAPABILITIES (CUSTOMIZABLE)  Wireless Communication 2.4GHz High-Frequency Radio Station  Maximum Communication Bandwidth & Distance 20Mbps, 1000m  MOVEMENT & WADE BARRIER ABILITY  Vehicle Speed 1m/s°  Parking Positioning Accuracy ±10mm  Gradeability >15°  Obstacle Crossing Ability 50mm  Wading Ability Ground Ponding<100mm	CONTROL MODE		
NAVIGATION SYSTEM  Navigation Method / Accuracy  COMMUNICATION CAPABILITIES (CUSTOMIZABLE)  Wireless Communication  Maximum Communication Bandwidth & Distance  MOVEMENT & WADE BARRIER ABILITY  Vehicle Speed  Parking Positioning Accuracy  Gradeability  Obstacle Crossing Ability  Wading Ability  Lidar, ±10mm  2.4GHz High-Frequency Radio Station  2.4GHz High-Frequency Radio Station  100mm	Control Mode	Auto / Manual Control	
Navigation Method / Accuracy       Lidar, ±10mm         COMMUNICATION CAPABILITIES (CUSTOMIZABLE)         Wireless Communication       2.4GHz High-Frequency Radio Station         Maximum Communication Bandwidth & Distance       20Mbps, 1000m         MOVEMENT & WADE BARRIER ABILITY         Vehicle Speed       1m/s°         Parking Positioning Accuracy       ±10mm         Gradeability       >15°         Obstacle Crossing Ability       50mm         Wading Ability       Ground Ponding<100mm	Control Terminal	PC, Remote Control	
COMMUNICATION CAPABILITIES (CUSTOMIZABLE)  Wireless Communication 2.4GHz High-Frequency Radio Station  Maximum Communication Bandwidth & Distance 20Mbps, 1000m  MOVEMENT & WADE BARRIER ABILITY  Vehicle Speed 1m/s°  Parking Positioning Accuracy ±10mm  Gradeability >15°  Obstacle Crossing Ability 50mm  Wading Ability Ground Ponding<100mm	NAVIGATION SYSTEM		
Wireless Communication       2.4GHz High-Frequency Radio Station         Maximum Communication Bandwidth & Distance       20Mbps, 1000m         MOVEMENT & WADE BARRIER ABILITY         Vehicle Speed       1m/s°         Parking Positioning Accuracy       ±10mm         Gradeability       >15°         Obstacle Crossing Ability       50mm         Wading Ability       Ground Ponding<100mm	Navigation Method / Accuracy	Lidar, ±10mm	
Wireless Communication       2.4GHz High-Frequency Radio Station         Maximum Communication Bandwidth & Distance       20Mbps, 1000m         MOVEMENT & WADE BARRIER ABILITY         Vehicle Speed       1m/s°         Parking Positioning Accuracy       ±10mm         Gradeability       >15°         Obstacle Crossing Ability       50mm         Wading Ability       Ground Ponding<100mm	COMMUNICATION CAPABILITIES (CUSTOMIZABLE)		
Maximum Communication Bandwidth & Distance  MOVEMENT & WADE BARRIER ABILITY  Vehicle Speed  Parking Positioning Accuracy  \$\pmathrm{		2.4GHz High-Frequency Radio Station	
Vehicle Speed     1m/s°       Parking Positioning Accuracy     ±10mm       Gradeability     >15°       Obstacle Crossing Ability     50mm       Wading Ability     Ground Ponding<100mm	Maximum Communication Bandwidth & Distance	20Mbps, 1000m	
Vehicle Speed     1m/s°       Parking Positioning Accuracy     ±10mm       Gradeability     >15°       Obstacle Crossing Ability     50mm       Wading Ability     Ground Ponding<100mm	MOVEMENT & WADE BARRIER ABILITY		
Gradeability >15°  Obstacle Crossing Ability 50mm  Wading Ability Ground Ponding<100mm		1m/s°	
Obstacle Crossing Ability50mmWading AbilityGround Ponding<100mm	Parking Positioning Accuracy	±10mm	
Wading Ability Ground Ponding<100mm	Gradeability	>15°	
	Obstacle Crossing Ability	50mm	
PROTECTION ABILITY	Wading Ability	Ground Ponding<100mm	
	PROTECTION ABILITY		
Body Protection Level IP55	Body Protection Level	IP55	
Extreme Anti-Collision & Anti-Drop Collision System Support	Extreme Anti-Collision & Anti-Drop Collision System	Support	
Dynamic Obstacle Avoidance System  Mechanical, Ultrasonic, Multi-Lidar Stereo Avoidance	Dynamic Obstacle Avoidance System	Mechanical, Ultrasonic, Multi-Lidar Stereo Avoidance	
BATTERY	BATTERY		
Maximum Battery Life >8 Hours	Maximum Battery Life	>8 Hours	
Battery Capacity & Life 36AH, Charge & Discharge Cycle≥1000 Times	Battery Capacity & Life	36AH, Charge & Discharge Cycle≥1000 Times	
SYSTEM WORKING ENVIRONMENT & PHYSICAL PARAMETERS			
Working Temperature -20°C ~ +60°C		_	
Working Voltage Alternating Current 220V, 50Hz			
Physical Dimension 815mm x 580mm x 930mm			
Weight 90kg		90kg	

## 4. ACCESSORIES











Robot Wheel (ROB) (Options)

Robot Dog (AIBO) (Options)

Cables Carrying Case SDK

Mellon (Singapore) Pte. Ltd.